# ADS310 Series Smart Single Phase Solar inverter

User Manual

# Preface

Thank you for choosing ADS310 series AC Drive. The ADS310 series is manufactured using high-quality components, material and incorporating the latest microprocessor technology available.

#### **Getting Started**

This manual will help in the installation, parameter setting, troubleshooting, and daily maintenance of the AC motor drive. To guarantee safe operation of the equipment, read the following safety guidelines before connecting power to the AC motor drive. Keep this operating manual handy and distribute to all users for reference.

ADS310 series drive is design to high standards of EMC. Conforms with the following standards:

CE marked for low voltage directive.

UL508C Power conversion equipment.

IEC664-1 Insulation coordination for equipment within low voltage system.

EN61000-2,3,4 Generic Immunity / Emissions standards (EMC) .

#### △ WARNING

Always read this manual thoroughly before using ADS310 series AC Motor Drives.

DANGER! AC input power must be disconnected before any maintenance. Do not connect or disconnect wires and connectors while power is applied to the circuit. Maintenance must be performed by qualified technicians.

CAUTION! There are highly sensitive MOS components on the printed circuit boards.

These components are especially sensitive to static electricity. To avoid damage to these components, do not touch these components or the circuit boards with metal objects or your bare hands.

**DANGER!** A charge may still remain in the DC-link capacitor with hazardous voltages even if the power has been turned off. To avoid personal injury, do not remove the cover of the AC drive until all "DISPLAY LED" lights on the digital keypad are off. Please note that there are live components exposed within the AC drive. Do not touch these live parts.

**CAUTION!** Ground the ADS310 using the ground terminal. The grounding method must comply with the laws of the country where the AC drive is to be installed. Refer to Basic Wiring Diagram.

**DANGER!** The AC drive may be destroyed beyond repair if incorrect cables are connected to the input/output terminals. Never connect the AC drive output terminals

U/T1, V/T2 directly to the AC main circuit power supply.

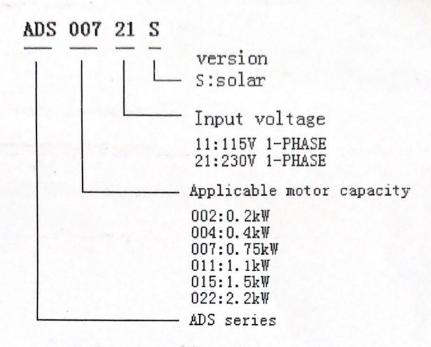
### **CHAPTER 1 RECEIVING AND INSPECTION**

This ADS310 AC drive has gone through rigorous quality control tests at the factory before shipment. After receiving the AC drive, please check for the following:

#### Receiving

- F Check to make sure that the package includes an AC drive, the User Manual, dust covers and rubber bushings.
- Inspect the unit to insure it was not damaged during shipment.
- Make sure that the part number indicated on the nameplate corresponds with the part number of your order.

## 1.1Model Explanation:



### 1.2 Technical specifications

Inverter model	Input voltage	Rated output power(kW	Rated input current(A)	Rated output current(A)	Adaptive motor	Base No.
ADS 002 21 S	1-phase	0.2	3.8	1.6	0.2	M1
ADS 004 21 S	220V	0.4	5.1	2.5	0.4	M1
ADS 007 21 S	±10% or	0.75	7.9	4	0.75	M1
ADS 011 21 S	200~380V	1.1	11.2	5.6	1.1	M1
ADS 015 21 S		1.5	14	7	1.5	M1
ADS 022 21 S		2.2	22.5	11	2.2	M1

1.3 Standard specifications

		Items	Specifications Single-phase 220V, 50/60Hz DC 200~380V
ler.	Voltage a	nd frequency	
Power		fluctuation	Voltage:±10% Frequency:±5%
	Control s		High performance vector control, inverter based on DSP
	Control n		vector control
	Automat	ic torque boost	Realize low frequency (1Hz) and large output torque contro under the V/F control mode.
	Accelerat	ion/deceleration	Time range is 0.0 to 600S.
	Over load	capability	Rated current 150% - 1 minute, rated current 180% - ; seconds
	Maximur	n frequency	0 to 400Hz
E	Carrier F	requency	0.5 to 16kHz; automatically adjust carrier frequency according to the load characteristics.
Control system	Input fre		Digital setting: 0.01Hz Analog setting: maximum frequency×0.1%
1.0	Speed ra	nge	1:100 (vector control )
Ş		peed precision	Vector control: ≤ ± 0.5% (rated synchronous speed)
	Torque re		≤ 40ms (vector control)
	DC brakii		DC braking frequency: 0.0Hz to max. frequency, braking time: 0.0 to 100.0 seconds, braking current value: 0.0% to 100.0%
		(F	Jog Frequency Range: 0.00Hz to max. frequency;
	Jog contr	rol	Jog Ac/deceleration time: 0.0s to 600.0s
	Multi-sp	eed operation	Achieve up to 3-speed operation through the control terminal
	<u> </u>	ic voltage	Automatically maintain a constant output voltage when the
	regulatio		voltage of electricity grid changes
Personalization function	Self-insp peripher power-or		After powering on, peripheral equipment will perform safety testing, such as ground, short circuit, etc.
Person	Quick cu	rrent limiting	The current limiting algorithm is used to reduce the inverter over current probability, and improve whole unit anti-interference capability.
		Running	Keyboard/terminal/communication
	<u>-</u>	Frequency	4 frequency settings available, including adjustable DC(0 to 10V), adjustable DC(4 to 20mA), panel potentiometer, etc.
	sign	Start signal	Rotate forward/reverse
50	Input signal	Multi-speed	At most 3-speed can be set(run by using the multi-function terminals or program)
Running		Emergency stop	Interrupt controller output
2		Fault reset	When the protection function is active, you can automatically omanually reset the fault condition.
	ignal	Running status	Motor status display, stop, ac/deceleration, constant speed, program running status.
	Output signal	Fault output	Contact capacity :normally closed contact 5A/AC 250V, normally open contact 3A/AC 250V, 1A/DC 30V.
	0	Analog output	Two-way analog output, 16 signals can be selected such as frequency, current, voltage and other, output signal range (0 to 10V / 0 to 20mA).

Items		ems	Specifications	
	Output signal		At most 3-way output, there are 40 signals each way	
	Run function	on .	Limit frequency, jump frequency, frequency compensation	
	Running command channel		Three channels: operation panel, control terminals and serial communication port.	
	Frequency	source	Total 5 frequency sources: multi-speed, analog voltage, analog current, communication , keypad potentiometer.	
	input tern	ninals	4 digital input terminals, compatible with active PNP or NPN input mode, 1 analog input terminals for voltage or current input.	
	Output ter	rminals	One relay output terminal;	
Protection function	Inverter p	rotection	Overvoltage protection, undervoltage protection, overcurrent protection, overload protection, overheat protection, overvoltage stall protection, , communication error	
ote Ju	Inverter fa	an control	Will work when the inverter is working	
	Paramete function	r protection	Protect inverter parameters by setting administrator Password and decoding	
Display	LED display keyboard	Running information	Monitoring objects including: running frequency, set frequency, bus voltage, output voltage, output current output power, analog Al value, motor Actual running speed	
_		Error message	At most save six times error message, and the fault code can be queried when the failure is occurred.	
	LED displa	зу	Display parameters	
Communi	RS485		The optional completely isolated RS485 communication module can communicate with the host computer.	
	Environm	ent temperature	-10 °C to 40 °C (temperature at 40 °C to 50 °C, please derating for use)	
	Storage to	emperature	-20 °C to 65 °C	
int	Environm	ent humidity	Less than 90% R.H, no condensation.	
ir.	Vibration		Below 5.9m/s² (= 0.6g)	
Environment	Application sites		Indoor where no sunlight or corrosive, explosive gas and water vapor, dust, flammable gas, oil mist, water vapor, drip or salt, etc.	
	Altitude	the second second	Below 1000m	
	Pollution	degree	2	
dard	Product standards	adopts safety s.	IEC61800-5-1:2007	
Product adopts safety standards.  Product adopts EMC standards.			IEC61800-3:2005	

# CHAPTER 2 STORAGE AND INSTALLATION

#### 2.1 Storage:

The AC drive should be kept in the shipping carton before installation. In order to retain the

warranty coverage, the AC drive should be stored properly when it is not to be used for an extended period of time.

### 2.2 Ambient Conditions:

Operation Air Temperature: -10°C to +40°C (14°F to 104°F)

Atmosphere pressure: 86 to 106 kPa

Installation Site Altitude: below 1000m

Storage Temperature: -20°C to +60°C (-4°F to 140°F)

Relative Humidity: Less than 90%, no condensation allowed

Atmosphere pressure: 86 to 106 kPa

Transportation Temperature: -20°C to +60°C (-4°F to 140°F)

Relative Humidity: Less than 90%, no condensation allowed

Atmosphere pressure: 86 to 106 kPa

#### 2.3 Installation:

#### CAUTION!

The control, power supply and motor leads must be laid separately. They must not be fed through the same cable conduit / trunking.

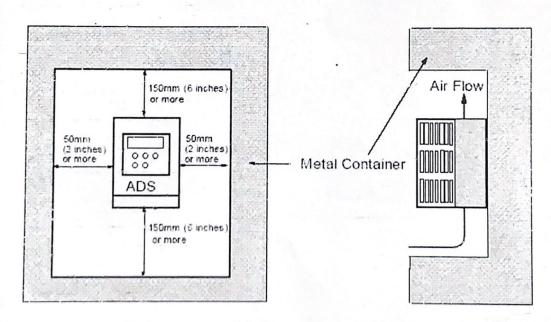
High voltage insulation test equipment must not be used on cables connected to the drive.

Improper installation of the AC drive will greatly reduce its life. Be sure to

observe the following precautions when selecting a mounting location.

#### Failure to observe these precautions may void the warranty!

- ♦ Do not mount the AC drive near heat-radiating elements or in direct sunlight.
- ❖ Do not install the AC drive in a place subjected to high temperature, high humidity, excessive vibration, corrosive gases or liquids, or airborne dust or metallic particles.
- ♦ Mount the AC drive vertically and do not restrict the air flow to the heat sink fins.
- The AC drive generates heat. Allow sufficient space around the unit for heat dissipation.



Minimum Clearances and Air Flow

# CHAPTER 3 WIRING

#### DANGER!

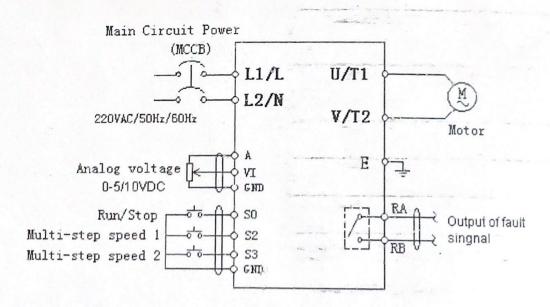
# 3.1 Hazardous Voltage

Before accessing the AC drive:

- Disconnect all power to the AC drive.
- Wait five minutes for DC bus capacitors discharge.

## 3.2 Basic Wiring Diagram

Users must connect wiring according to the circuit diagram shown below. Please follow all National and State wiring codes, when wiring the ADS310.



### 3.3 Terminal Explanations

Terminal Symbol	Explanation of Terminal Function
L1/L, L2/N	AC line input terminals
U/T1,V/T2	AC drive output terminals motor connections
E	Earth Ground

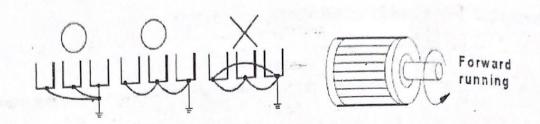
# 3.4 Control Terminals Explanations

wire Gauge : 22-24AWG

Terminal Symbols	Terminal Functions
SO SO	Run/Stop
S2	Multi-step speed 1
53	Multi-step speed 2
- A	Potentiometer power source (+5/10VDC)
VI	Analog voltage input (0~-5/10VDC)
GND	Common signal

## 3.5 Wiring Notes: PLEASE READ PRIOR TO INSTALLATION.

- 1. CAUTION: Do not connect the AC power to the U/T1, V/T2 terminals, as it will damage the AC drive.
- 2. WARNING: Ensure all screws are tightened to the proper torque rating.
- 3. During installation, follow all local electrical, construction, and safety codes for the country the drive is to be installed in.
- 4. Ensure that the appropriate protective devices (circuit breaker or fuses) are connected between the power supply and AC drive.
- 5. Make sure that the leads are connected correctly and the AC drive is properly grounded. (Ground resistance should not exceed 0.1 .)
- 6. Use ground leads that comply with AWG/MCM standards and keep them as short as possible.
- 7. Multiple ADS310 units can be installed in one location. All the units should be grounded directly to a common ground terminal. The ADS310 ground terminals may also be connected in parallel, as shown in the figure below. **Ensure there** are no ground loops.



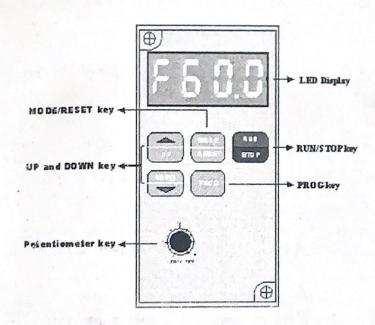
- 8. When the AC drive output terminals U/T1, V/T2 are connected to the motor terminals U/T1, V/T2 respectively, the motor will rotate counterclockwise (as viewed from the shaft ends of the motor) when a forward operation command is received.
- 9. Make sure that the power source is capable of supplying the correct voltage and required current to the AC drive.
- 10. Do not attach or remove wiring when power is applied to the AC drive.
- 11. Do not monitor the signals on the circuit board while the AC drive is in operation.
- 12. Route the power and control wires separately, or at 90 \_ angle to each other.
- 13. When using a GFCI (Ground Fault Circuit Interrupt), select current sensor with sensitivity of 200mA, and not less than 0.1-second detection to avoid nuisance tripping.

# **CHAPTER 4 DIGITAL KEYPAD OPERATION**

# 4.1 Description of Digital Keypad

This digital keypad includes two parts: Display panel and keypad. Display panel provides the parameter display and shows operation status of the AC drive.

Keypad provides programming interface between users and AC drives.



#### Mode

By pressing the "mode" key repetitively, the display will show status at the AC drive such as the reference frequency, output frequency, and output current. If the drive stops due to a fault, correct the fault first, then press this key to reset the drive.

#### PROG

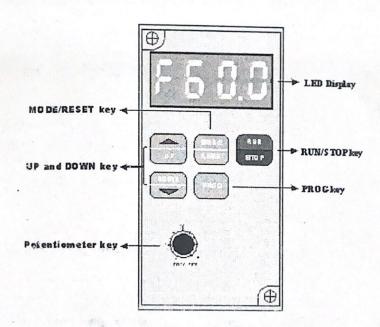
Pressing the "PROG" key will store entered data or can show factory stored data.

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#### PROG

Pressing the "PROG" key will store entered data or can show factory stored data.

#### Run/Stop

Press to Start or Stop the AC drive operation. This key can only be used to Stop the AC Drive when the drive is controlled by the External Control Terminals.

#### Up / Down

Press the "Up" or "Down" keys momentarily to change parameter settings.

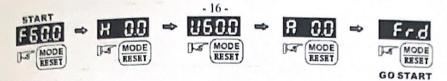
These keys may also be used to scroll through different operating values or parameters. Pressing the "Up" or "Down" key momentarily, will change the parameter settings in single-unit increments. To quickly run through the range of settings, press down and hold the key.

Display Message	Descriptions
F50.0	The AC drive Master Frequency
H500	The Actual Operation Frequency present at terminals U/T1, V/T2.
U3 (O)	The DC-BUS voltage
6550	The output voltage
0-	The specified parameter group
0-00	The specified parameter
6 D	The actual value stored within the specified parameter.
End	"End" displays for approximately 0.5 second if input has been accepted. After a parameter value has been set, the new value is automatically stored in memory. To modify an entry, use the "UP" and "DOWN" keys.



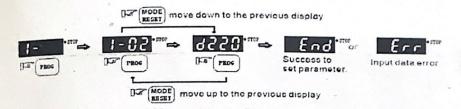
"Err" displays, if the input is invalid.

## **Setting Mode**



NOTE: In the selection mode, press "PROG" key to set the parameters.

### **Setting Parameters**



**NOTE:** In the parameter setting mode, you can press to return the selecting mode.

#### To shift data



### **CHAPTER 5 SUMMARY OF PARAMETER SETTINGS**

	Parameters	Functions	Settings	Factory Setting
☆	0-03	Start-up display of AC drive	0: F (Frequency command) 1: H (output frequency) 2: U (user-defined unit) 3: A (output current)	0
☆	0-04	Content of Multi-Function Display	0: Display User-Defined Unit (u) 3: Display DC-BUS Voltage (u) 4: Display output voltage (E)	С

de marine i	0-07	Unlock password Input	0 to 999	0
-	0-08	Password Set	0 to 999	0
	1-00	Maximum operation Freq.	50.0 ~ 400Hz	50.0
-	1-01	Maximum setting Freq.	10.0 ~ 400Hz	50.0
-	0-07	Unlock password Input	0 to 999	0
-	0-08	Password Set	0 to 999	0
4	1-09	Accel time	0.1 ~ 600 Sec	5.0
H H	1-10	Decel time	0.1 ~ 600 Sec	10.0
I	2-00	Source of frequency command	0: Digital keypad  1: 0 ~ 10V from AVI  2: 4 ~ 20mA from AVI  3: Controlled by V.R on drive  4: RS-485 communication interface	1
	2-01	Source of operation command	0: By digital keypad 1: By external terminals, keypad STOP enable 2: By external terminals, keypad STOP disable 3: By RS-485 communication interface, keypad STOP enable 4: By RS-485 communication interface, keypad STOP disable	1
2	4-00	Potentiometer bias freq.	0.0 ~ 100%	0.0
W.	4-01	Potentiometer bias polarity	0: positive bias 1: negative bias	С
4	4-02	Potentiometer freq. gain	1~200%	100
	4-04	Multi-function input terminal 1 (S1)	0: not used 1: S0: RUN/STOP	1
	4-05	Multi-function input terminal 2(S2)	6: RESET 7: multi-step speed command 1	7
	4-06	Multi-function input terminal 3(S3)	8: multi-step speed command 2	8
+	5-00	1st step speed freq.	0.0 ~ 400Hz	Ö
+	5-01	2nd step speed freq.	0.0 ~ 400Hz	0
+	5-02	3rd step speed freq."	0.0 ~ 400Hz	0
	6-07	Present fault recor	0: No fault occurred	
	6-08	Second most rece fault record	1: oc (over current) 2: ov (over voltage)	
	6-09	Third most recent fault record	3: oH (over heat) 4: oL (over load)	•
	6-10	Forth most recent fault record	5: oL1 (electronic thermal)	0
1	6-11	Fifth most recent fault record		
	6-12	Sixth most recent fault record		

	Parameter	Functions		Settings	Factor Setting
Tr.	9-00	Communication address		1~247	1
**	9-01	Transmission speed	1	): Baud rate 4800 L: Baud rate 9600 : Baud rate 19200	1
公	9-02	Transmission fault treatment	0: War 1: Wa 2: Wa	n and continue running arn and ramp to stop arn and coasting stop warn and keep running	0
☆	9-03	Modbus communication watchdog timer		0: Disable 1~20: 1 ~ 20 Sec	0
立	9-04	Communication protocol	ASC mod	0: 7,N,2 1: 7,E,1 2: 7,O,1 3: 8,N,2 4: 8,E,1 5: 8,O,1	0
			mod	6: 8,N,2 7: 8,E,1 8: 8,O,1	

Switch 1	Switch 2	Parameters	Speed
OFF	OFF		The current speed setting value
ON	OFF	5-00	1st step speed freq.
OFF	ON	5-01	2nd step speed freq.
ON	ON	5-02	3rd step speed freq.

### **CHAPTER 6 Troubleshooting and Fault Information**

The ADS310 AC drive has a comprehensive fault diagnostic system that includes several different alarms and fault messages. Once a fault is detected, the corresponding protective functions will be activated. The following faults are displayed on the AC drive digital keypad.

**NOTE**: Faults can be cleared by a reset from the keypad (pressing "MODE" key)

# Common Problems and Solutions:

Fault Name	Fault Descriptions	Corrective Actions
oc	The AC drive detects an abnormal	Check whether the motors     horsepower corresponds to the
	increase in current.	AC drive output power.
		2. Check the wiring connections between the AC drive and motor
		for possible short circuits.  3. Increase the Acceleration time.
		4. Check for possible excessive loading conditions at the motor.
		5. If there are any abnormal conditions when operating the AC drive after short-circuit being removed, it should be sent back to manufacturer.
ου	The AC drive detects that the DC bus voltage has exceeded its maximum allowable value.	<ol> <li>Check whether the input voltage falls</li> <li>within the rated AC drive input voltage.</li> <li>Check for possible voltage</li> </ol>
- Lange (4.5)		transients.

		3. Bus over-voltage may also be
		caused by motor regeneration.
NA.		Increase the decel time.
οН	The AC drive temperature sensor	1. Ensure that the ambient
	detects excessive heat.	temperature falls within the
	a transfer of the second	specified temperature range.
		2. Make sure that the ventilation
		holes are not obstructed.
		3. Remove any foreign objects on
		the heatsinks and check for
		possible dirty heat sink fins.
		4. Provide enough spacing for
*10 - 3 - 6		adequate ventilation.
Lu	The AC drive detects that the DC	Check whether the input voltage
	bus voltage has fallen below its	falls within the rated AC drive's
	minimum value.	input voltage.
οL	The AC drive detects excessive	1. Check whether the motor is
	drive output current.	overloaded.
	A Marine 27	2. Increase the AC drive's output
		capacity.
oL I	Internal electronic overload trip	1. Check for possible motor
		overload.
	The second secon	2. Check electronic thermal
		overload setting.

	The second second second second	3. Increase motor capacity.
oL2	Motor overload.	1. Reduce the motor load.
HPF	Hardware protection failure	Return to the factory.

## **CHAPTER 7 SPECIFICATIONS**

	230V							
Model N	lomber ADS	002	004	007	011	015	022	
Aplicab	0.2	0.4	0.75	1.1	1.5	2.2		
Output Rating	Max. Outp	1-phase corresponds to input voltage						
	Rated Freq	1.0~60Hz						
Power	Rated Input Current (A)		4.9	6.5	9.7	12	15.7	24
and the second second	Input voltage Tolerance		Single –phase 180~264V 50/60Hz					
and the second s	Frequency	5%						
Control	Control system		SVPWM (Sinusoidal Pulse Width Modulation carried frequency 10kHz)					
Characteristics	Output Frequency Resolution		0.1Hz					
	Incoord or		150% of rated current for 1 minute					
	Overload E	ndurance	150% of	rated o	current to	0( 1 11111		
			150% of 0.1~600	many thrown	7 1			
	Overtoad E	l Time		Sec. (ca	n be set			
	Over!oad E	l Time	0.1~600	Sec. (ca	n be set ustable	individ	ually)	
Operating	Overload En	l Time	0.1~600 V/F patt	Sec. (ca	ustable	individ	ually)	
Operating Characteristics	Overload En Accel/Dece V/F pattern Stall Preven	Time	0.1~600 V/F patt 200%, se	Sec. (caern adjecting c	ustable of Rated keys	individ	ually)	

	Operation Setting	Keypad	Setting by RUN//STOP keys				
	Signal	External Signal	S0,S2,S3 can be combined to offer various modes of operation,				
Other Function			Over-Voltage Stall Prevention, Fault Records, Over-Current Stall Prevention, Momentary Power Loss restart, Frequency Limits, Parameter Lock/Reset				
Protection			Over Voltage, Over Current, Under Voltage, Overload, Electronic thermal, Overheating, Self-testing				
Cooling			Forced air-cooling				
Environment		Installation Location	Altitude 1,000 m or below, keep from corrosive gasses, liquid and dust				
		Ambient Temperature	-10°C-40°C (Non-Condensing and not frozen)				
		Storage Temperature	-20°C to 60°C				
		Ambient Humidity	Below 90%RH (non-condensing)				
		/ibration	9.80665m/s2(1G) less than 20Hz, 5.88m/s2 (0.6Gat) 20 to 50Hz				

Any modification shall be subject to the delivery condition, and no beforehand or further notice will be given for all changes in design and size.